

Earth and Planetary Materials

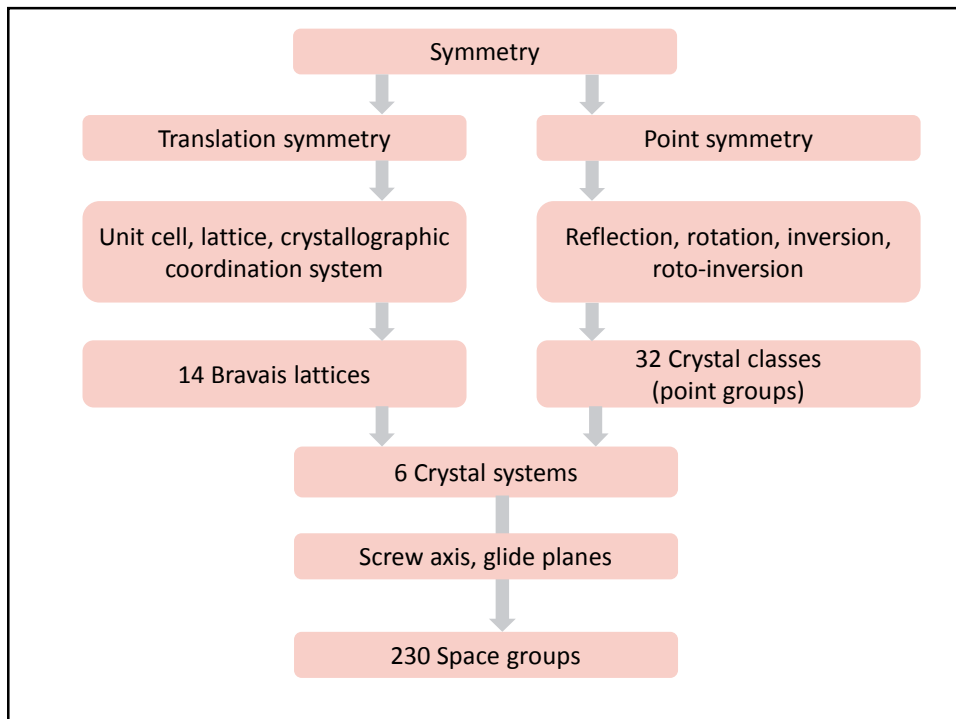
Spring 2013

Lecture 11
2013.02.13

Midterm exam

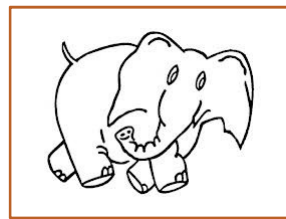
- 2/25 (Monday)
- Office hours:
 - 2/18 (M) 10-11am
 - 2/20 (W) 10-11am
 - 2/21 (Th) 11am-1pm
 - No office hour 2/25

Point symmetry



Structure (or pattern) = motif + symmetry operations

- Motif: Unit of pattern – what is repeated
- Symmetry operations – how to repeat
 - Application of the symmetry operation leaves the pattern unchanged
 - Or, starting with one motif, application of the symmetry operation generates the other motifs in the pattern



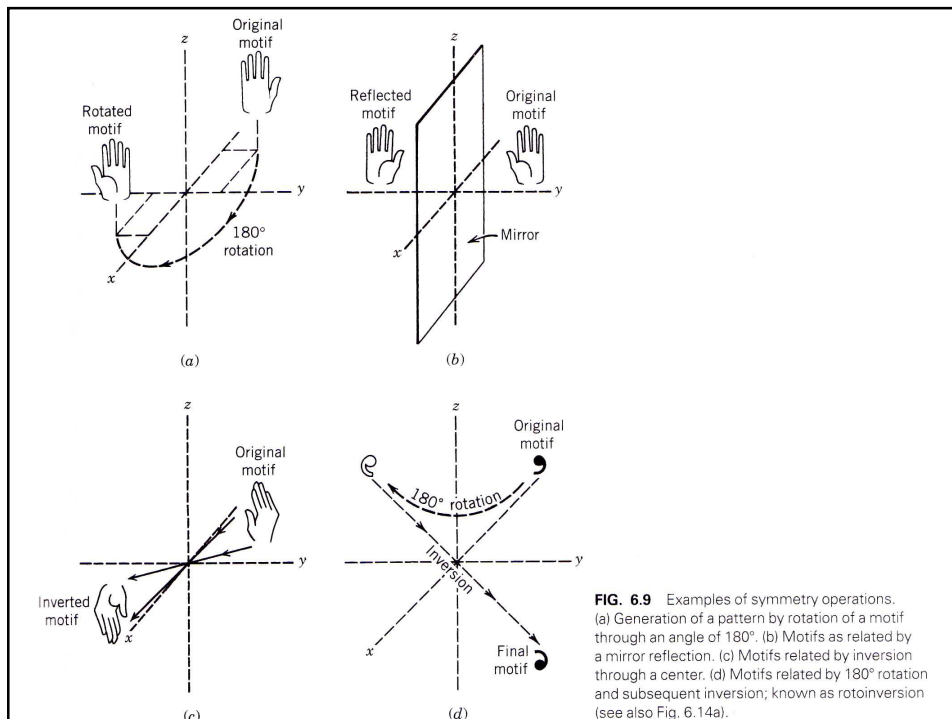
motif

Symmetry operation
(reflection)



Types of symmetry operation

- Rotation
- Reflection
- Inversion
- Roto-inversion



Symmetry operation

- The movement that leaves the pattern unchanged

Symmetry element

- The object about which the movement takes place

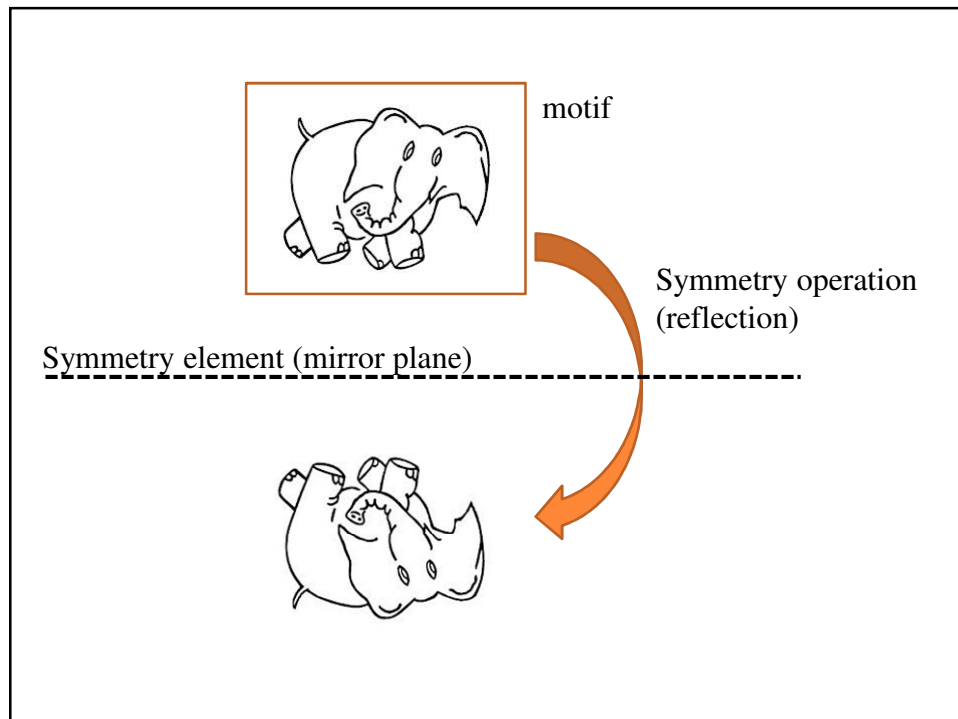


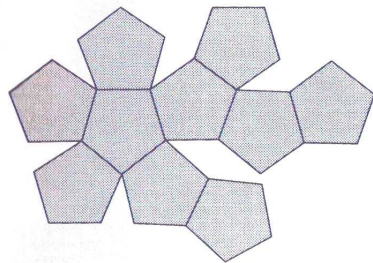
Table 6.1 Nomenclature for Point Symmetry

Symmetry Element	Symmetry Operation	Symmetry Symbol	Hermann-Mauguin Notation
Rotation Axis	Rotation	A_1, A_2, A_3, A_4, A_6	1, 2, 3, 4, 6
Mirror Plane	Reflection	m	\bar{m}
Center of Symmetry	Inversion	i	$\bar{1}$
Rotoinversion	Rotation + Inversion	$\bar{A}_1 = i, \bar{A}_2, \bar{A}_3, \bar{A}_4, \bar{A}_6$	$\bar{1}, m(=2), 3, 4, 6$

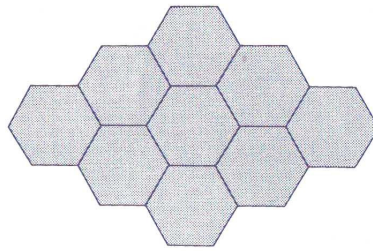
Rotation

- 2 (2-fold axis); rotation by $360^\circ/2 = 180^\circ$ leaves the pattern unchanged
- 3 (3-fold axis); rotation by $360^\circ/3 = 120^\circ$ leaves the pattern unchanged
- likewise for 4-fold and 6-fold axes

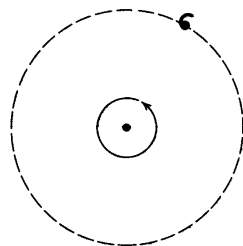
- Only need to consider 2-, 3-, 4-, and 6-fold axes
- All others (e.g., 5-fold rotation) are incompatible with translational symmetry (you can't tile a floor with pentagons!)



(a)

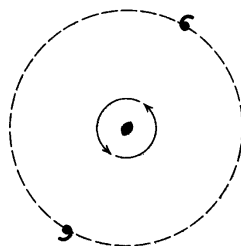


(b)



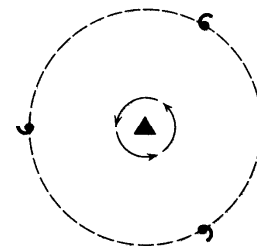
1 turn of 360° rotation

1



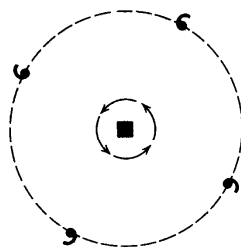
2 turns of 180° rotation

2



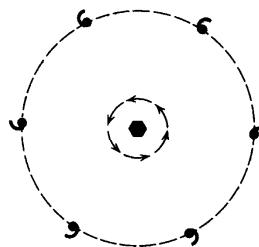
3 turns of 120° rotation

3



4 turns of 90° rotation

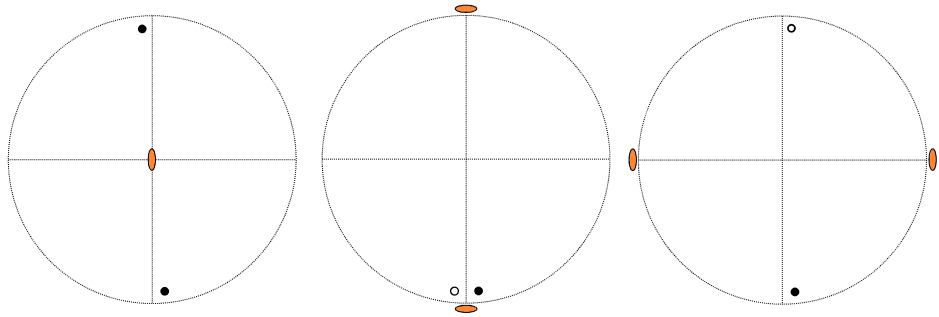
4



6 turns of 60° rotation

6

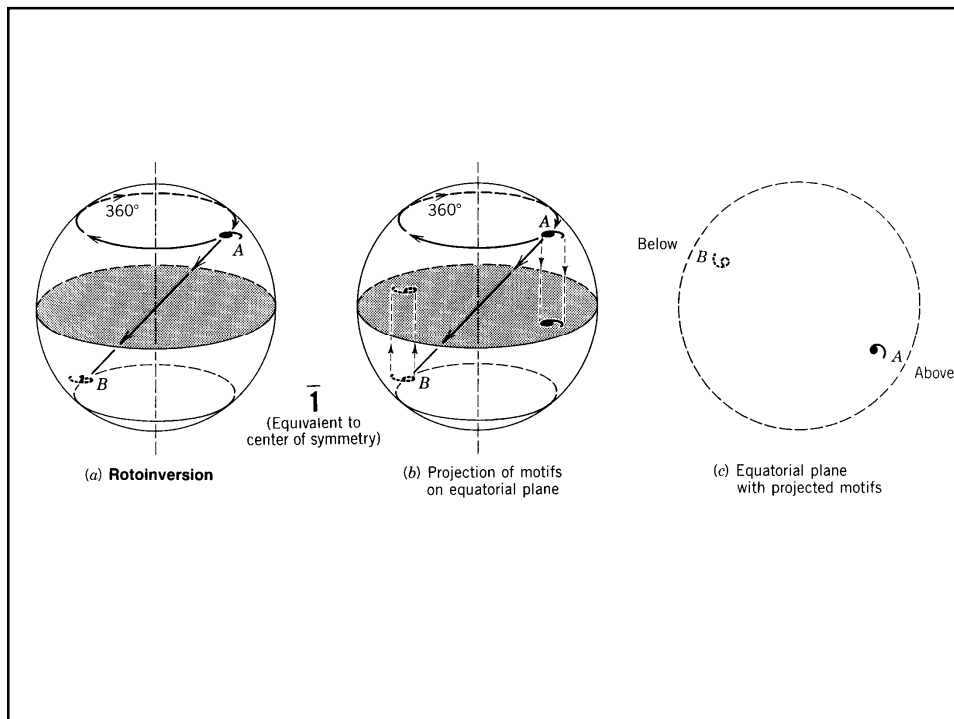
Example: Stereograms showing patterns with a 2-fold symmetry, with different orientations for the rotation axis (from left to right, parallel to c , a , and b axes)

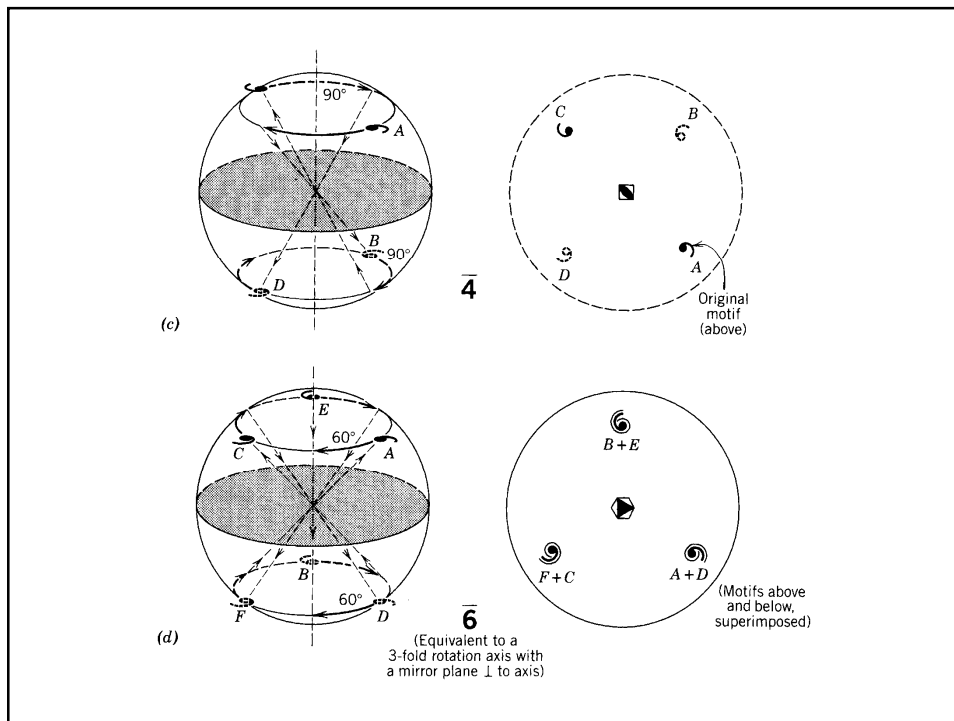
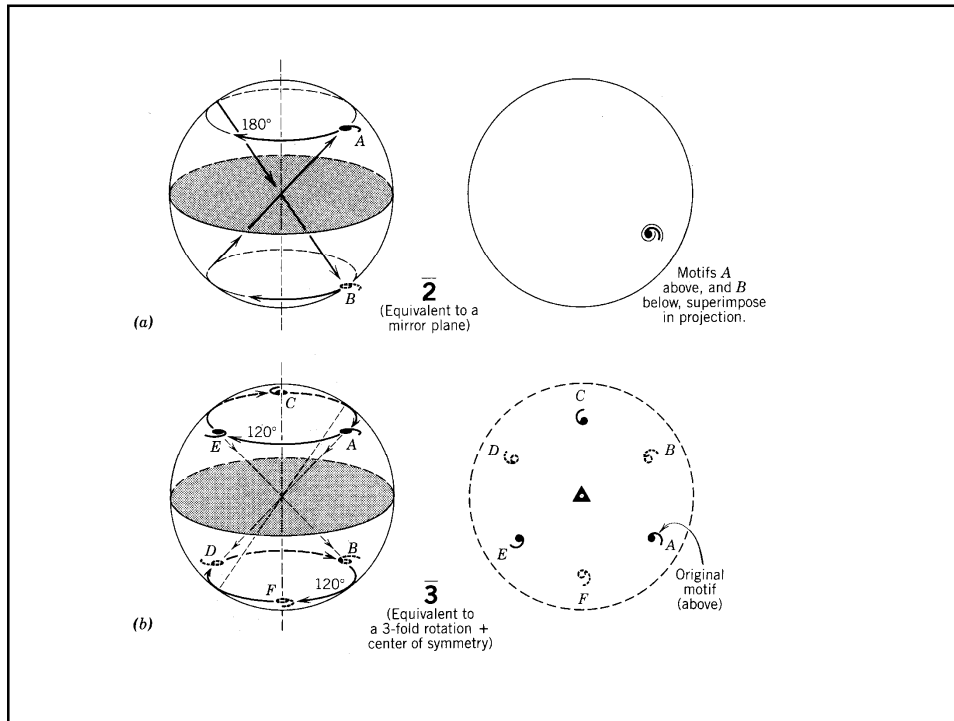


Roto-inversion

- Rotation followed by inversion through the origin
- Inversion creates a point $(-x,-y,-z)$ for each point (x,y,z)

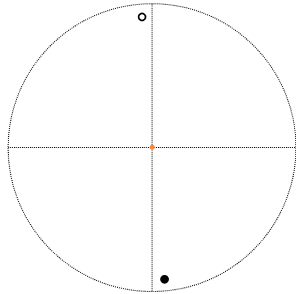
- $\bar{1}$: same as an inversion center, often denoted as “*i*”
- $\bar{2}$: same as a mirror plane, often denoted as “*m*” and shown as a heavy solid line
- $\bar{3}$: same as a 3-fold axis with an inversion center
- $\bar{4}$: high-symmetry axis of a tetrahedron (edge to edge)
- $\bar{6}$: same as 3-fold axis with a perpendicular mirror



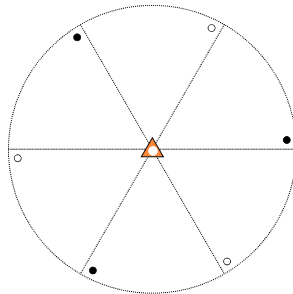


- Example: Roto-inversion axes and the resulting patterns

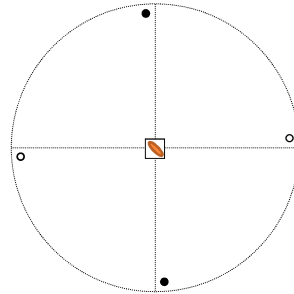
$\bar{1} (= i)$



$\bar{3} (= 3 + i)$

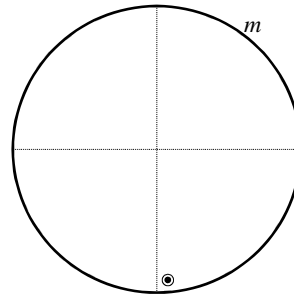
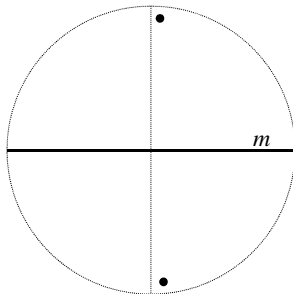
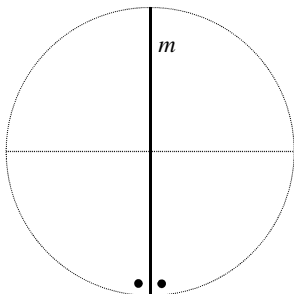


$\bar{4}$



Example: Reflection ($\bar{2}$, or m) symmetry – mirror plane

- From left to right, the $\bar{2}$ axes are perpendicular to **b** (left), **a** (center), and **c** (right) axes



Combination of symmetry operations

Example – combination of rotations

- If there is a 4-fold axis parallel to c and a 2-fold axis parallel to a , then there must also be a 2-fold axis parallel to b
- More examples: Klein p121-128

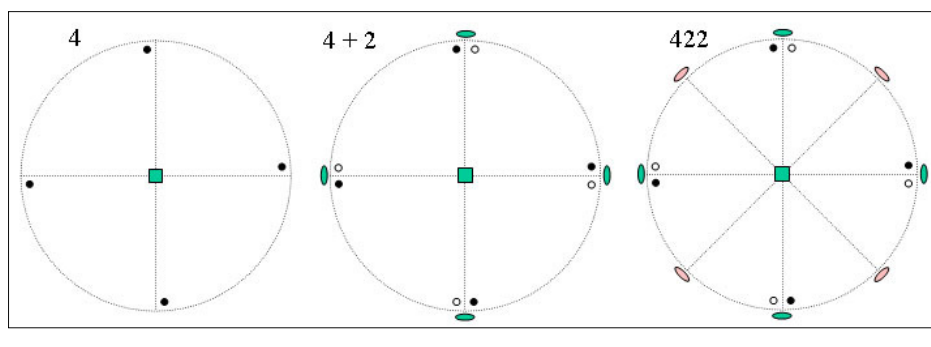
Point Groups

self-consistent set of point symmetry operations

- Only certain combinations of point symmetry elements are compatible
- 32 point groups

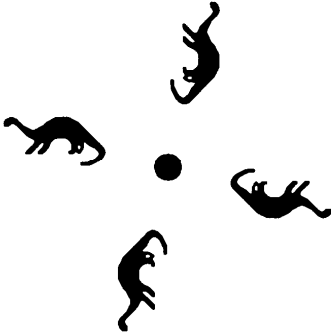
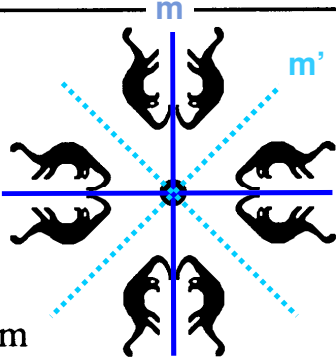
Example





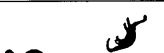



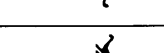

- Point group 4
- Addition of one 2-fold axis that is parallel to the a_1 and a_2 axes
- This automatically gives another 2-fold axis between the a_1 and a_2 axes



Naming point groups

- Highest symmetry axis is listed first
- Mirror planes perpendicular to an n-fold rotation axes are shown as n/m:
 - Example: 4/m (“four over m”) = mirror perpendicular to 4-fold axis
- Mirror planes that are parallel to the main rotation axes are shown as just m
 - Example: 4mm

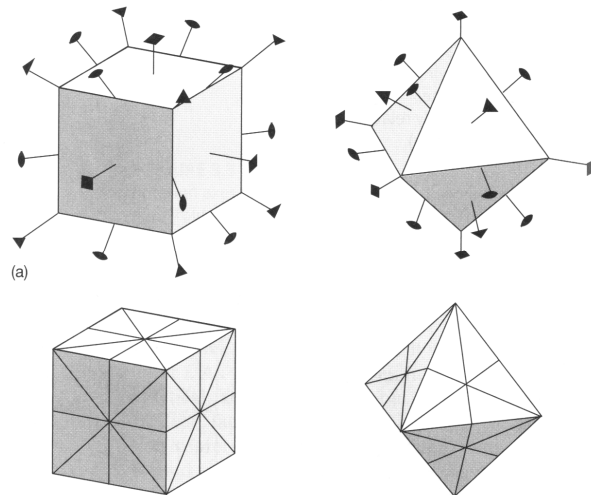
 <p style="font-size: 24pt; font-weight: bold; margin-top: 10px;">4</p>	 <p style="font-size: 24pt; font-weight: bold; margin-top: 10px;">4mm</p>
<p>mirror “m” is generated automatically by the combination of mirror “m” and the rotation axis “4”. “m” is different from “m” in how it related the dinosaurs.</p>	

1		1m	
2		2m	
3		3m	
4		4m	
6		6m	

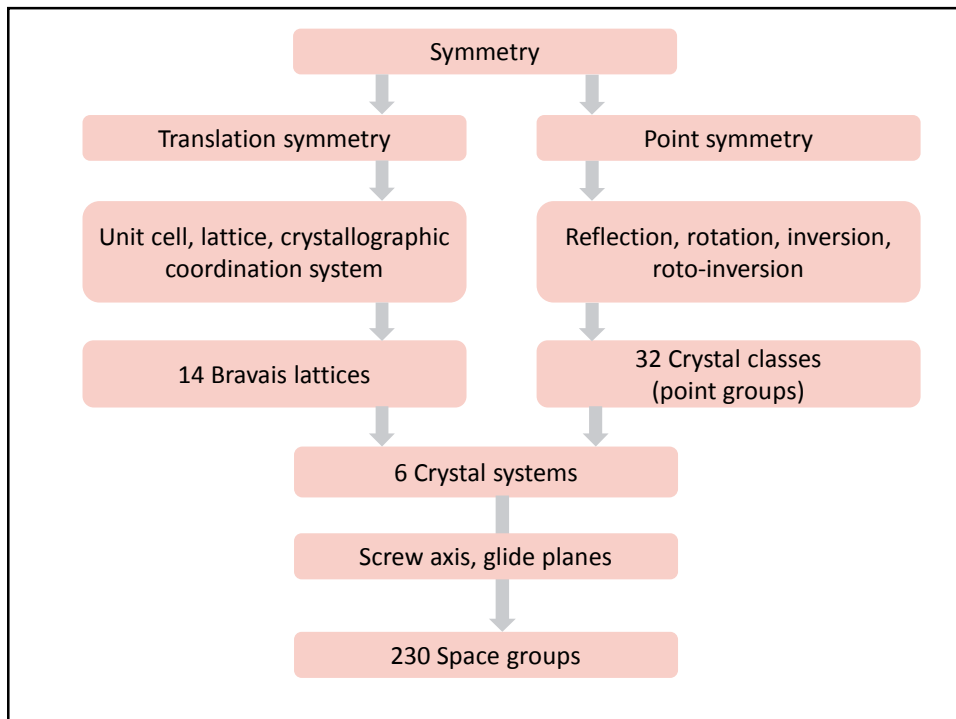
Cubic systems

- Contain intersecting 3-fold or 4-fold axes
- The cube, octahedron, and tetrahedron are objects with a lot of intersecting point symmetry

► **FIGURE 9.8**
Cube and octahedron: (a) The rotation axis in a cube and an octahedron have identical orientations. Lenses, triangles and squares show 2-fold, 3-fold and 4-fold axes of symmetry. (b) The mirror planes in a cube and octahedron are also oriented identically.



Crystal systems



- Point symmetry and translational symmetry must be compatible, so that each of the types of unit cell (Bravais Lattice) has a corresponding compatible point symmetry

- Example 1: if there is a 4-fold axis parallel to \mathbf{c} , then the \mathbf{a} and \mathbf{b} unit cell dimensions must be the same, because a 90° rotation of \mathbf{a} makes it equal to \mathbf{b} . So, the tetragonal system is characterized by a tetragonal unit cell ($\mathbf{a} = \mathbf{b} \neq \mathbf{c}; \alpha = \beta = \gamma = 90^\circ$), and a single 4-fold rotation or roto-inversion axis (4 or $\bar{4}$). The \mathbf{c} -axis parallels the unique (4-fold) axis.

- Example 2: The monoclinic system contains either a 2-fold axis parallel to **b** or a mirror plane perpendicular to **b**. This symmetry forces the **a-c** plane to be perpendicular to **b**; so that the angles $\alpha = \gamma = 90^\circ$. You should be able to prove to yourself that a 2-fold axis parallel to **b** only works if the angle between **a** and **b** is 90° . There is no constraint on the angle between **a** and **c** ($\beta \neq 90^\circ$), and all the cell edge lengths can be different and still compatible with point symmetry.

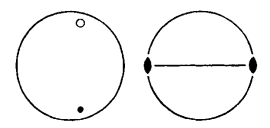

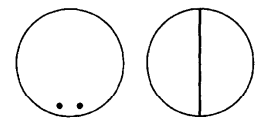



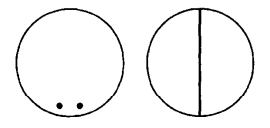
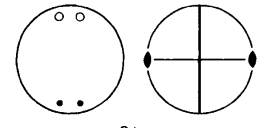



The six crystal systems

You should be able to describe the types of unit cell and essential point symmetry.

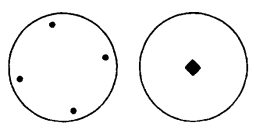
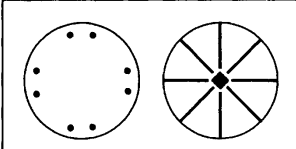
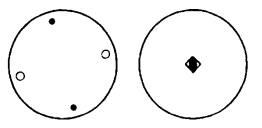
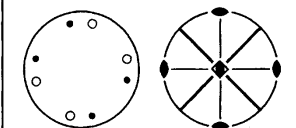
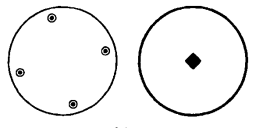
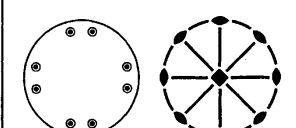
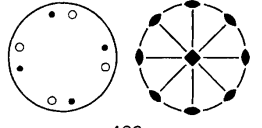
Trigonal/Hexagonal

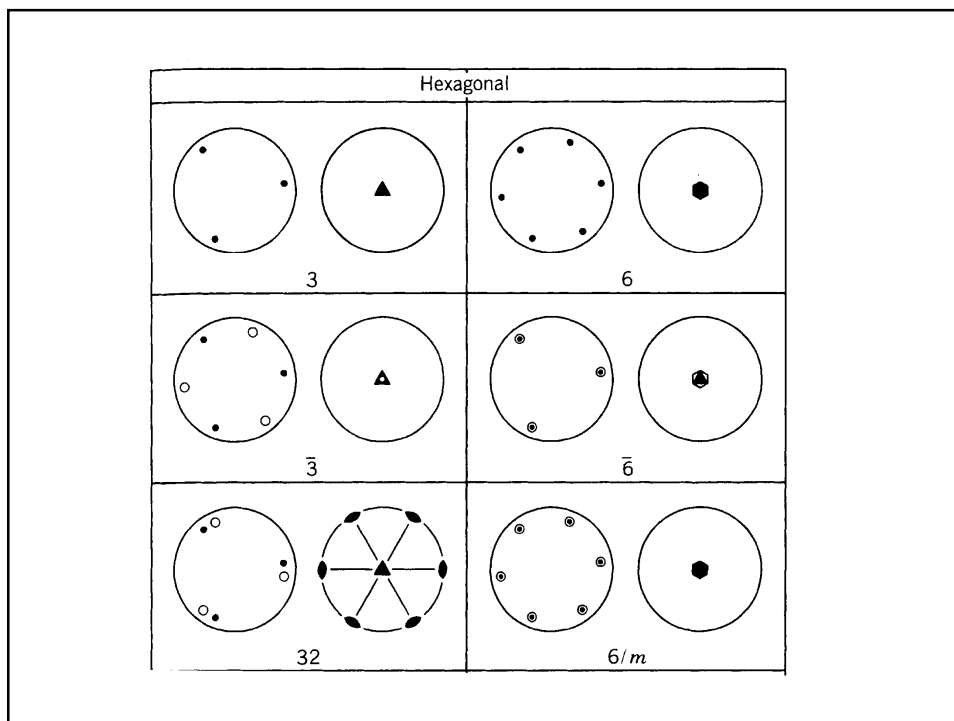
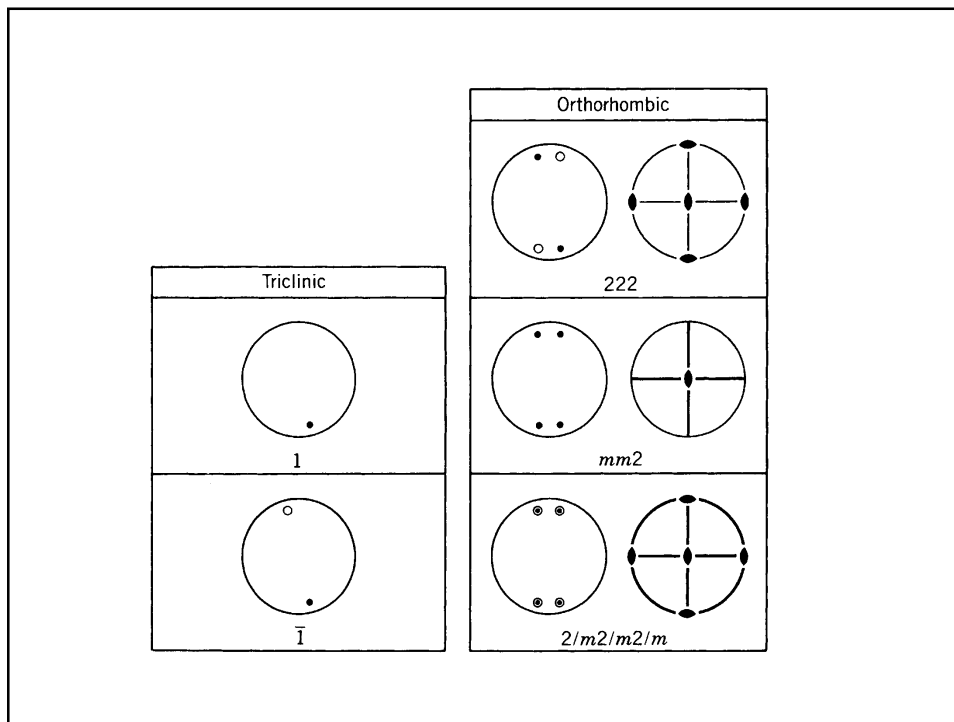
Crystal system	Unit cell dimensions	Essential symmetry	Bravais lattices
Triclinic	$a \neq b \neq c$; $\alpha \neq \beta \neq \gamma$	None	P
Monoclinic	$a \neq b \neq c$ $\alpha = \gamma = 90^\circ$ $\neq \beta$	A diad (2-fold) axis	P, C
Orthorhombic	$a \neq b \neq c$ $\alpha = \beta = \gamma = 90^\circ$	Three mutually perpendicular diad axes	P, C, I, F
Tetragonal	$a = b \neq c$ $\alpha = \beta = \gamma = 90^\circ$	A tetrad (4-fold) axis	P, I
Cubic	$a = b = c$ $\alpha = \beta = \gamma = 90^\circ$	Four triad (3-fold) axes	P, I, F
Trigonal*	$a = b = c$ $120^\circ > \alpha = \beta = \gamma \neq 90^\circ$	A triad axis	R (rhombohedral)
Hexagonal	$a = b \neq c$ $\alpha = \beta = 90^\circ$, $\gamma = 120^\circ$	A hexad (6-fold) axis	P

* Crystals in the trigonal system may be described by an hexagonal unit cell, even though they do not have a hexad rotation axis.

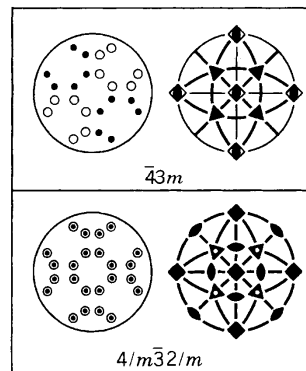
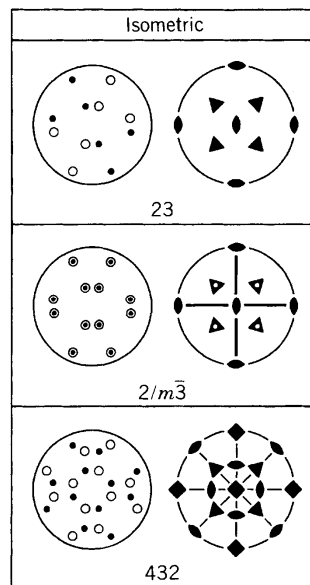
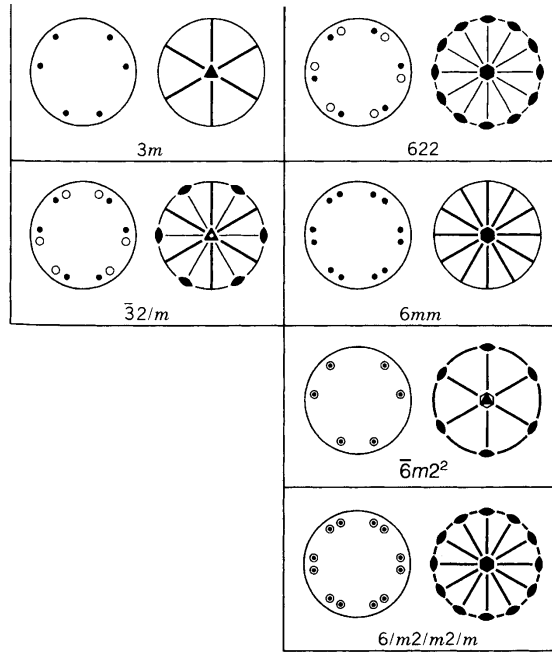
Written symbols	Graphical symbols	Monoclinic
1	None	
2		
3		
4		
6		
m	—	
$\bar{1}$ (=center)	} *See caption	
$\bar{2}$ (=m)		
$\bar{3}$ (=3 plus center)		
$\bar{4}$		
$\bar{6}$ (=3/m)		

Motif above page •
Motif below page ○

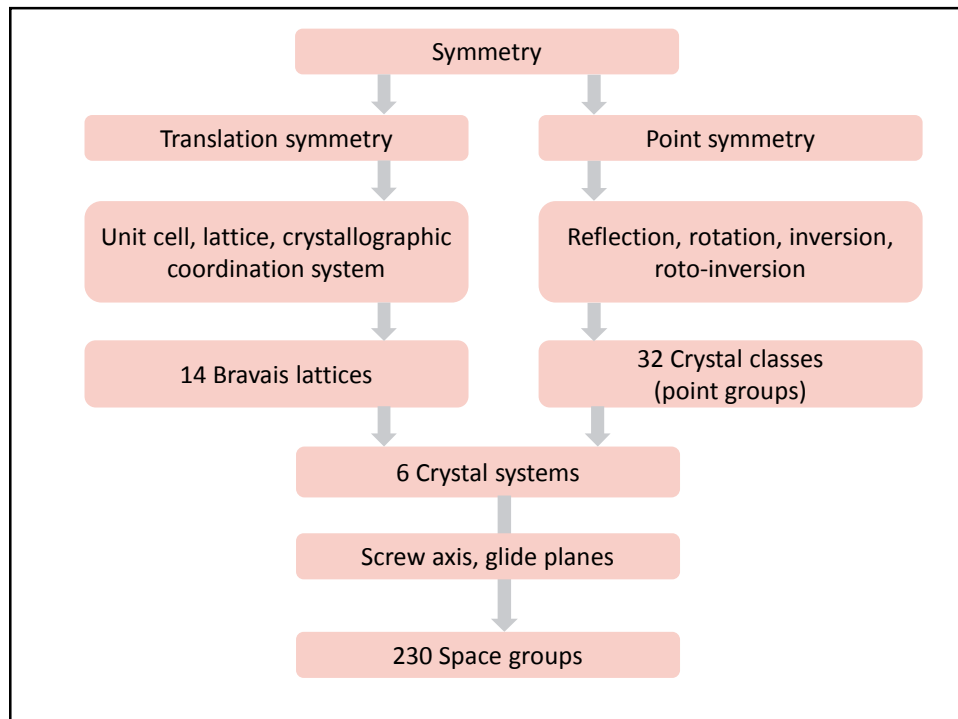
Tetragonal	
	
4	$4m$
	
4	$\bar{4}2m$
	
$4/m$	$4/m2/m2/m$
	
422	



More hexagonal



Space groups



Space groups

Point symmetry plus translational symmetry

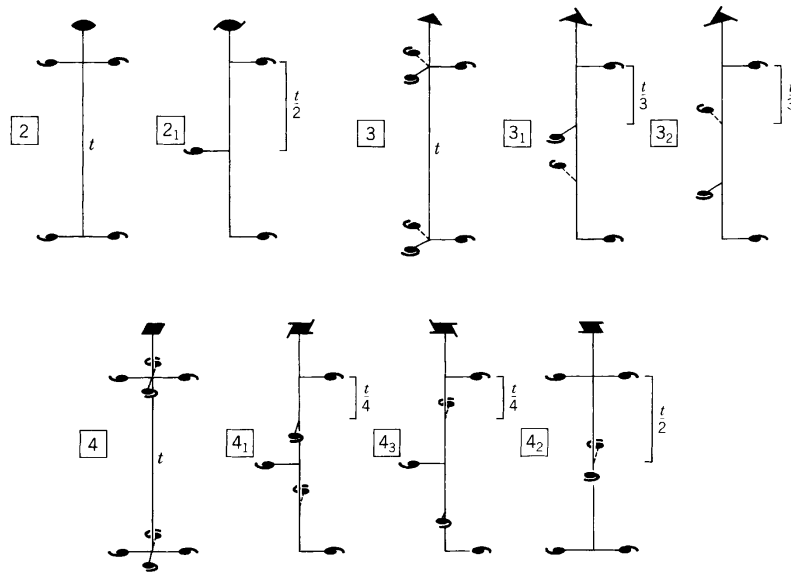
→ 230 space groups

Screw axis

Rotation plus a translation of a fraction of a unit cell

- Example: 2_1 is a rotation of 180 followed by translation of 1/2 unit cell.

Screw axes: rotation + translation

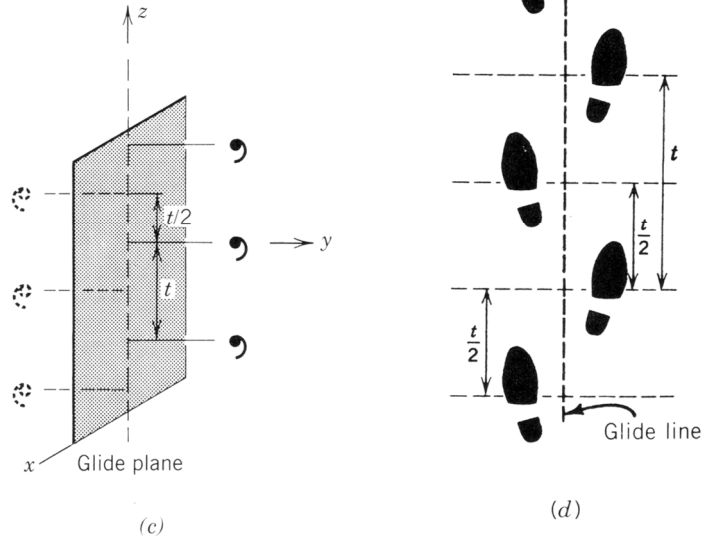


Glide plane

Reflection plus a translation of a fraction of a unit cell

- Example: foot prints of someone walking

Glide planes: reflection + translation



COMMON MINERALS CLASSIFIED ACCORDING TO CRYSTAL CLASS

	<i>Class symmetry</i>	<i>Example</i>
Cubic	$\frac{4}{m} \bar{3} \frac{2}{m}$	Cu, Au, pentlandite, galena, halite, sylvite, fluorite, cuprite, periclase, spinel, magnetite, chromite, garnet
	$\frac{2}{m} \bar{3}$	Pyrite
	$\bar{4} 3 m$	Sphalerite, lazurite, tetrahedrite, diamond
	$4 3 2$	—
	$2 3$	—
Tetragonal	$\frac{4}{m} \frac{2}{m} \frac{2}{m}$	Rutile, cassiterite, pyrolusite, zircon
	$4 m m$	—
	$\frac{4}{m}$	Leucite
	4	—
	$\bar{4} 2 m$	Bornite, chalcopyrite
	$4 2 2$	Cristobalite
Hexagonal	$\frac{6}{m} \frac{2}{m} \frac{2}{m}$	Graphite, pyrrhotite, covellite, molybdenite, beryl
	$6 m m$	Wurtzite, zincite, ice
	$\frac{6}{m}$	Apatite
	6	Nepheline
	$6 2 2$	High quartz
	$\bar{6} m 2$	—
	$\bar{6}$	—

	<i>Class symmetry</i>	<i>Example</i>
Trigonal	$\bar{3} \frac{2}{m}$	Corundum, hematite, brucite, magnesite, siderite, smithsonite, calcite, rhodochrosite
	$3 m$	Tourmaline
	$\bar{3}$	Ilmenite, dolomite
	$3 2$	Low quartz, cinnabar
Orthorhombic	3	—
	$\frac{2}{m} \frac{2}{m} \frac{2}{m}$	α -S, stibnite, marcasite, chrysoberyl, perovskite, columbite-tantalite, goethite, aragonite, strontianite, witherite, cerrusite, anhydrite, celestite, barite, anglesite, olivine, sillimanite, andalusite, topaz, staurolite, zoisite, orthopyroxenes, orthoamphiboles
	$m m 2$	Chalcocite
Monoclinic	$2 2 2$	—
	$\frac{2}{m}$	Arsenopyrite, realgar, orpiment, psilomelane, azurite, malachite, borax, gypsum, monazite, lazulite, carnotite, sphene, clinozoisite, epidote, allanite, clinopyroxenes, clinoamphiboles, talc, muscovite, biotite, chlorites, kaolinite, antigorite, chrysotile, sanidine, orthoclase, tridymite
Triclinic	2	—
	m	—
	$\bar{1}$	Turquoise, kyanite, chlorites, kaolinite, microcline, plagioclase
	1	—